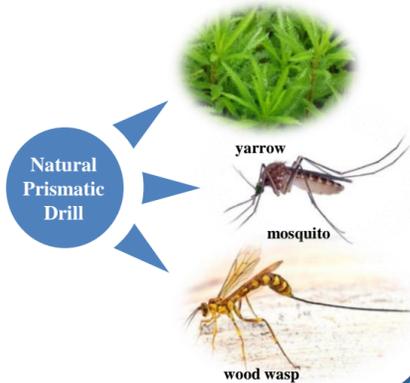
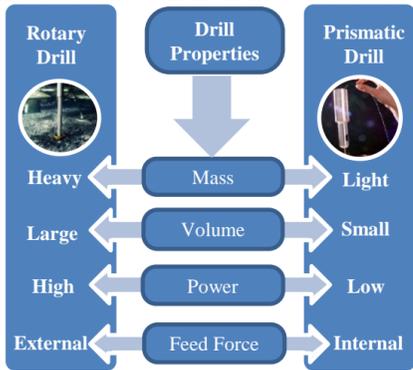




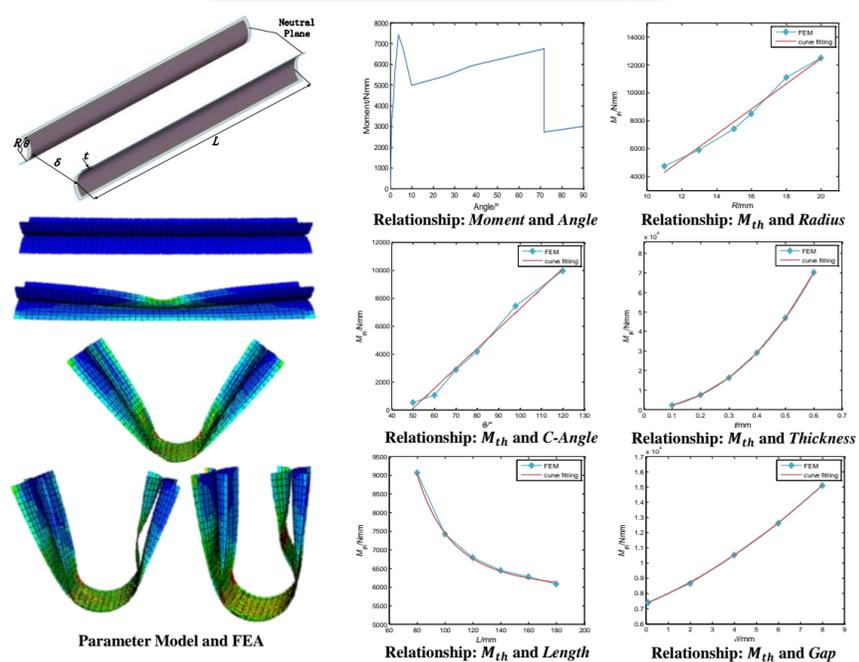
Three-valves Bionic Sampling Drill Inspired by Wood Wasp

Abstract

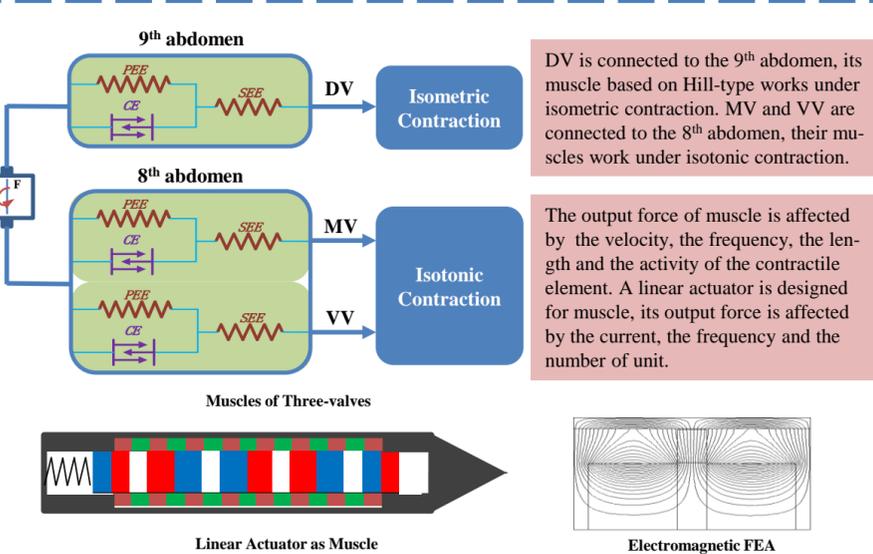
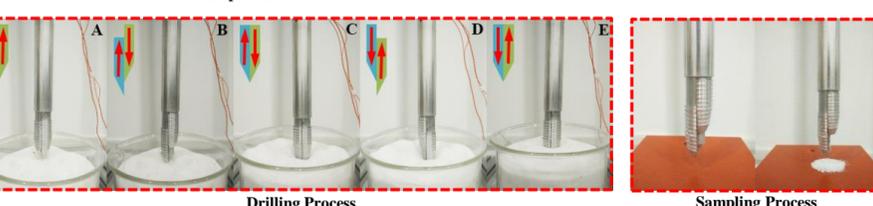
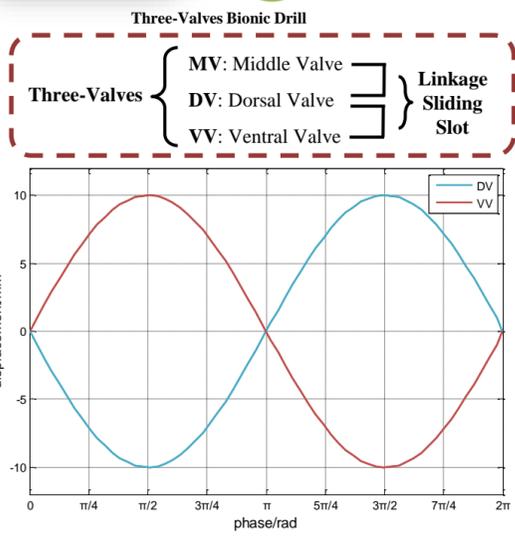
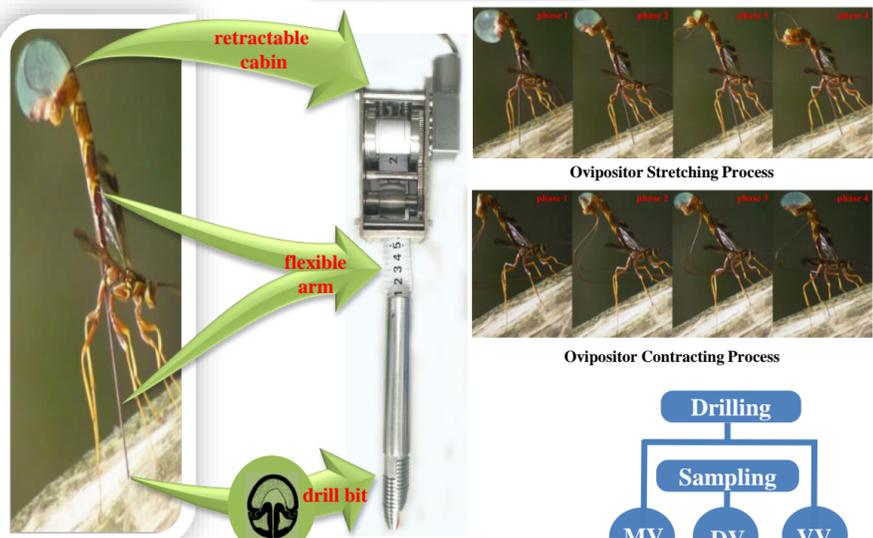
Drilling and sampling are important in space exploration. Although rotary drill technology is mature, it is limited in low gravity environment. However, the movement of natural drill is prismatic. Wood wasp has an immensely slender ovipositor, its valves can bore through the trunk to lay their eggs. Inspired by wood wasp, we proposed a three-valves bionic sampling drill which is composed of three parts: the Retractable cabin, the flexible arm and the drill bit. By observing the muscle contraction, the 8th abdomen contractile form is isotonic contraction, the 9th abdomen is isometric contraction. A linear actuator is for muscle. It is significant for mechanism research of novel drill in space exploration.



Simulation: Flexible Arm

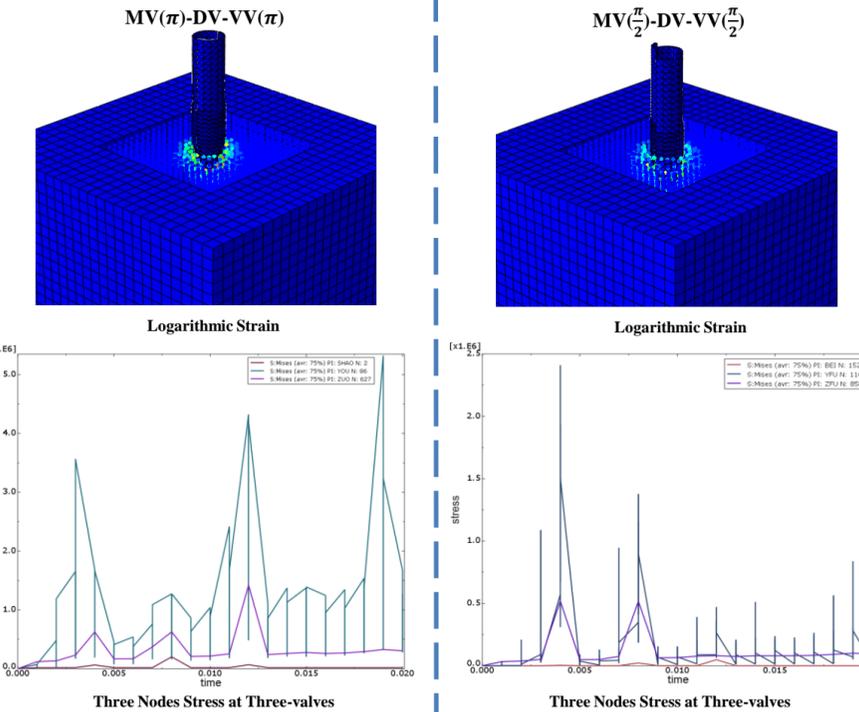


Sampling Drill



SPH: Drill-Lunar Soil

Lunar soil is composed of discrete particles, researching on the interaction between the different configuration drill bit and lunar soil by SPH (smoothed particle hydrodynamics) methods.



Conclusion

- Prismatic drilling, MV & VV for drilling, DV for sampling
- Linear actuator is similar to a contractile element of muscle
- Flexible arm with higher flexural and torsional stiffness, no bulging
- Different three-valves configuration affects the drill bit force

Publications & Patents

- [1] the National Science Foundation of China (51175494): Study on Spatial Expandable Structure Based on the Development Mechanism of Lepidoptera Insects
- [2] A Novel Low Velocity Robotic Penetrator Based on Ampere Force[M]. ICIRA.2017.
- [3] Retractable Bionic Sampler.CN107036842A.2017.
- [4] A Self-excited Penetrator.CN107040116A.2017.

